

TF, non-self-gravitating disk (DM everywhere dominant)

$$M_{\Delta} = \frac{4\pi}{3} \Delta \rho_{\text{crit}} R_{\Delta}^3$$

$$V_{\Delta} = \frac{GM_{\Delta}}{R_{\Delta}} \quad \text{"virial" quantities}$$

combining these with  $\rho_{\text{crit}} = \frac{3H_0^2}{8\pi G}$  gives

$$M_{\Delta} = \left(\frac{\Delta}{2}\right)^{-1/2} \left(\frac{1}{GH_0}\right) V_{\Delta}^3$$

so  $M_{\Delta} \approx C V_{\Delta}^3$

$$M_b = f_b M_{\Delta}$$

$$V_b = f_v V_{\Delta}$$

$$\frac{M_b}{f_b} = C \left(\frac{V_b}{f_v}\right)^3$$

$f_b = 0.15$  universal baryon fraction  $f_b = \frac{\Omega_b}{\Omega_{\text{DM}}}$

$f_{\Delta} = ?$  disk fraction = 1 only constraint

$f_v = f(v) \approx \text{unity} \rightarrow 1-1.3$  typically

should increase w/  $\Sigma$  & therefore with  $L$

if  $f_b$  &  $f_v$  constant,

$$M_b \sim V_b^3$$

slope too shallow,  $f_v(\Sigma): 3 \rightarrow 3.3 \pm 0.2$

so infer  $f_b \propto V_b$  (or  $f_v$  or both)

adiabatic compression

more fine-tuning, feedback

observed baryon content of bound structures  
a strong function of mass: halo-by-halo missing baryon problem

## Scaling relations

### Tully-Fisher

self gravitating disks:

$$v^2 = \frac{GM}{r}$$

M disk dominated

$$v^4 = \frac{G^2 M^2}{r^2}$$

$$\Sigma = \frac{M}{r^2} = \text{surface density enclosed by } r$$

$$v^4 = G^2 M \Sigma$$

$$M = \gamma L$$

or observationally

$$v^4 = G^2 \gamma^2 L I$$

$$I = \gamma \Sigma$$

↳ surface brightness

$\gamma = \text{dynamical } M/L$

i.e.  $L \propto v^4$  provided  $\gamma \neq I$  constant.

It was once thought all galaxies had the same surface brightness (Freeman's Law).

This derivation predicts a shift in TF with surface brightness  $I$ . Such a shift is not observed. Consequently, there is a fine-tuning:

$$\gamma^2 I = \text{constant}$$

$$\text{so } I \sim \gamma^{-1/2}$$

lower surface brightness galaxies must be progressively more DM dominated

## Example feedback scheme (Dutton 2009 MNRAS, 396, 126)

Supernova drives outflows, which are assumed to move at the local escape velocity, to minimize mass removal. ( $< v_{esc}$  does it escape  
 $> v_{esc}$  moves less mass for same energy)

Energy driven wind model:

$$\Delta M_{\text{eject}}(R) = \frac{2 E_{\text{EFB}} \eta_{\text{SN}} E_{\text{SN}} \Delta M_{*}(R)}{v_{\text{esc}}^2(R)}$$

↑
↑

ejected mass from radius R
 mass of stars formed at radius R

$$E_{\text{SN}} \approx 10^{51} \text{ erg} = 5 \times 10^7 \text{ km}^2 \text{ s}^{-2} M_{\odot}$$

$$\eta_{\text{SN}} = 8.3 \times 10^{-3} \text{ \# SN per } M_{\odot} \text{ of stars formed (this \# for a Chabrier IMF)}$$

$E_{\text{EFB}}$  = fraction of kinetic energy injected into wind

usually a large \# in simulations (0.25 - 1)

usually a small \# observed (0.02 - 0.1)

Momentum driven wind model:

$$\Delta M_{\text{eject}}(R) = \frac{E_{\text{EFB}} P_{\text{SN}} \eta_{\text{SN}} \Delta M_{*}(R)}{v_{\text{esc}}(R)}$$

$$P_{\text{SN}} = 3 \times 10^4 M_{\odot} \text{ km s}^{-1} \text{ is momentum produced by one SN}$$

$E_{\text{EFB}}$  is again the coupling efficiency to the ISM

This formulation maximizes the impact of SN.